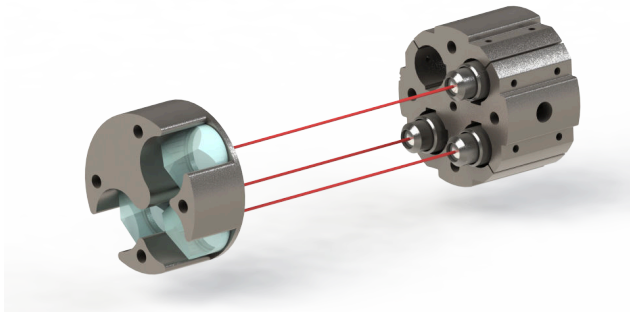


# PicoScale Angular Measurement Assembly - Specification Sheet



**Figure 1.** Sensor Head Assembly.

The **PICOSCALE** Angular Measurement Assembly (AMA) consists of a sensor head holder with three **PICOSCALE** C03 sensor heads in an L-shaped configuration (Figure 1). The three sensor heads are pre-aligned for maximum parallelism. In order to allow a large angular working range, a matching target assembly consisting of three retro reflectors is supplied. Optionally a fourth sensor head can be mounted to the sensor head assembly and a flat surface mirror to the retro reflector assembly, in order to allow a reliable zeroing by adjusting to the maximum intensity of the fourth beam. The sensor and the retro reflector assembly can be mounted using standard opto-mechanical equipment.

## 1. OPTICAL PROPERTIES

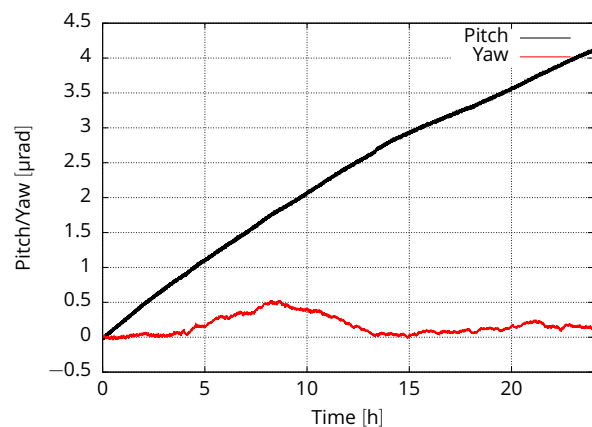
The AMA features an angular working range of  $\pm 10^\circ$  for one angle and  $\pm 7^\circ$  simultaneously for both angles. As the sensor heads measure the displacement of their individual targets with picometer resolution, the AMA allows angular measurements with a resolution of single nano-radians. The position stability under thermally controlled conditions is better than  $0.5 \mu\text{rad}$  per hour, as can be seen from the measurement data in Figure 2. For this measurement, the sensor head was mounted with the help of the included M4 thread, whereas the retro reflector holder was mounted in a 1" optics holder and fastened by a retaining ring.

## 2. SOFTWARE SUPPORT

In the small-angle approximation, the angle can be calculated straightforwardly by subtracting the signals of two adjacent sensor heads and dividing by their distance. Using the **PICOSCALE** Calculation System firmware module (PS-SP-CS) allows real-time calculation of angles directly. Thus, the angle data can be displayed or streamed into a data file without the need

**Table 1.** Summary of specifications.

Property	Value
Angular range (pitch/yaw)	$>\pm 10^\circ$ (pitch <u>or</u> yaw)
	$>\pm 7^\circ$ (pitch <u>and</u> yaw)
Resolution	$\approx 1 \text{ nrad}$
Stability	$< 0.5 \mu\text{rad/h}$
Sensor head separation	10.5 mm
Outer diameter	25.4 mm (1")



**Figure 2.** Angular stability data of the AMA measured over 24 hours in a temperature-controlled chamber.

for post-processing. The look-up table function of the Calculation System allows to calculate the precise angles even outside the range of the small-angle approximation. The correct configuration of the look-up table with the necessary trigonometric functions is supplied as a pre-set configuration ready to load into the **PICOSCALE** software. The distance of the laser beams is given in the data sheets.

## 3. ORDER CODE

Please contact SmarAct to find the optimal sensor head assembly for your application.

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