

SmarArt 🔊	Direct input						Stared Pases	
SmarAcr	Lower Limit	Position	Upper Limit				-	
PERFECT NOTION	×	0,400000	(nn)	Xe	X+	IN	Home Home	
300	τ	0,000000	(ren)	γ.	¥+	IN	Start Pose	
and the second	x	0,500000	(eed)	z-	Z+	INV	Fotation Z+	
	Position Step	0,200000	(mm)				Rotation Z-	<u> </u>
1 0	Raufe					In study		
SmarPod Controller	63	-300,000	[ref]	RX-	RX+	IN		
	83	100,000	[ref]	RV-	R3(+	IN	i mpty	1100
Step Standby	10	500 800	101	62-	62+	IN	The empty	1000
Stapped Standby Holdina Moving	Angia Sap 100,000 (m ⁻¹)						in mady	
Universidable Force	Celeved	MovelNew	Meye to Zen		Speed (min		in ampty	5 2 3
							in mpty	
Reference Referenced	Pastiens	res pre	nen Lorges		-	e l		
Measurer SP	Toolk Pase	Robur	Noise Shov	Fange	Hold 20			
MCS Configuration Invalid	Cations		Prost Paint		Coordinate Sv		Protect All	Unprotect All

SMARPOD Control Software

Main Features:

- Can handle different **SMAR**POD configurations, incl. position of the Pivot point.
- Allows to store up to 10 **SMAR**POD poses (absolute axis positions) which can easily be recalled with a mouse-click.
- Several possibilities to move the SMARPOD including your computer mouse, SMARPOD hand controller or a 6D mouse.

The **SMAR**POD Control Software is a graphical user interface, which can control all current **SMAR**POD models.